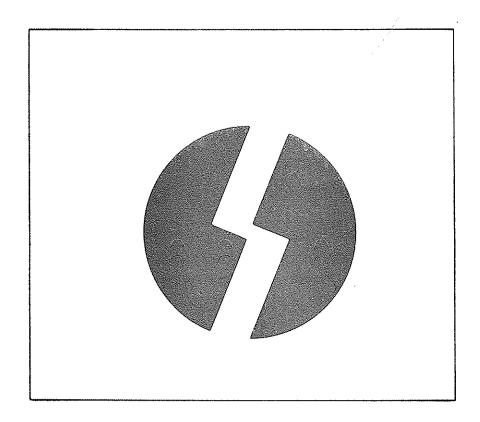
PUNCH ON #1 -

Sunair



OPERATION AND
MAINTENANCE MANUAL

1000 WATT
ANTENNA COUPLER

GCU-1100

WARRANTY POLICY

MARINE AND GROUND PRODUCTS

Sunair Electronics warrants equipment manufactured by it to be free from defects in material or workmanship, under normal use for which intended, for the lesser of one (1) year from the date of purchase or 18 months from date of shipment by Sunair.

Sunair will repair or replace, at its option, any defective component of the equipment (excluding tubes, crystals, fuses-pilot lights and solid state devices on which the warranty is limited to 90 days and on the conditions herein stated) returned to it at its factory, transportation prepaid, within such warranty period.

For a period of 90 days from date of purchase Sunair will repair any defective equipment returned to it at its factory, transportation charges prepaid. No reimbursement will be made for non-factory repair charges.

This warranty is void if equipment is modified or repaired without authorization, subjected to misuse, abuse, accident, water damage or other neglect, or has its serial number defaced or removed, or if warranty registration card is not returned to Sunair within 10 days of date of purchase.

THIS WARRANTY IS ESPECIALLY IN LIEU OF ANY AND ALL OTHER WARRANTIES EXPRESSED OR IMPLIED, INCLUDING ANY IMPLIED WARRANTY OF MERCHANTABILITY OR FITNESS FOR A PARTICULAR PURPOSE. The obligation and responsibility of Sunair shall be limited to that expressly provided herein and Sunair shall not be liable for consequential or other damage or expense whatsoever therefore or by reason thereof.

Sunair reserves the right to make changes in design or additions to or improvements in its equipment without obligation to install such additions or improvements in equipment theretofore manufactured.

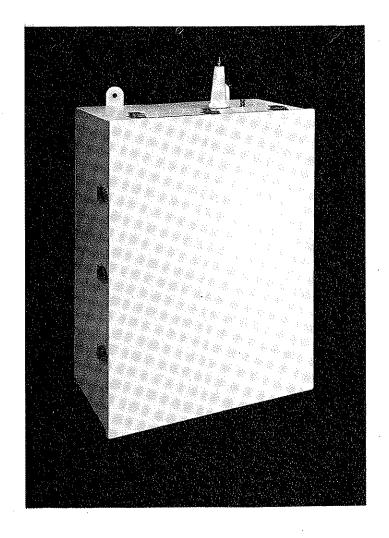
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sunair electronics, inc.

3101 S. W. 3rd Avenue, Fort Lauderdale, Florida 33315 USA



OPERATION AND MAINTENANCE MANUAL

1000 WATT ANTENNA COUPLER

GCU-1100

1st EDITION, 1 MAY, 1974 MANUAL PART NUMBER 5026-0009

GCU-1100 TABLE OF CONTENTS

SECTI	ON	PAGE NO
r	GENERAL INFORMATION	I-1
	1.1 Purpose Of Instruction Book 1.1.1 Purpose of Equipment	I-1
	1.2 Equipment Description	I-1
	1.3 Electrical Specification	I-2
	1.4 Equipment Supplied	I-2
	1.5 Equipment Required	I-2
	1.6 Optional Equipment	I-3
II	INSTALLATION	
	2.1 Unpacking And Inspection of Equipment	II-1
		II-1
	2.2 Return of Equipment to Sunair	II-1
	2.3 Installation Procedure	
	2.3.1 General Installation Requirements	II-2
	2.3.2 Mounting Considerations	II-3
	2.3.3 Installation of Remote Control & RF Cables	II-4
	2.4 Preliminary Electrical Checks	II-5
III	OPERATION	III-l
	3.1 Test Equipment Required	III-1
	3.2 RF Network, Final Adjustment, Preliminary	
	3.3 RF Network, Tuning Procedure	III-1
		III-2
IV	THEORY OF OPERATION	IV-1
	4.1 Antenna Tuning Network	
	4.1.1 General	IV-1
	4.1.2 Input Shunt Capacitance	IV-1
	4.1.3 Series Inductances	IV-l
	4.1.4 Output Shunt Capacitance	IV-2
	4.2 Circuit Efficiency	•
	4.3 Control Circuit	
	4.4 Series Inductor Position Servo System	IV-3
	4.5 Servo Amplifier	T17 3

TABLE OF CONTENTS (cont'd)

SECTION	PAGE NO.
V MAINTENANCE AND REPAIR	V-1
5.1 Periodic Maintenance	. V-1
5.2 Troubleshooting and Repair	V-2
5.2.2 Timing Period Adjustments	V-2
5.2.3 Voltage Measurements, Tune Control Board P	C-1 V-2
5.2.4 Voltage Measurements, Servo Amplifier Boar	
5.2.5 Servo Amplifier Check	V-3
5.2.6 Spark Cap Adjustment	V-4
5.2.7 High Voltage Output Capacitor Selector Sw	vitch V-4
5.3 R.F. Network Adjustments	
VI APPENDIX	
6.1 Electrical Parts List	VI-1
Garage Spares List	VI-4

LIST OF ILLUSTRATIONS

FIGUR	E	PAGE
2-1	Outline Configuration	II-4
4-1	Inductor Position Servo System	IV-4
4-2	Servo Amplifier Output Bridge	IV-5
5-1	GCU-1100 Top View	V- 6
5-2	GCU-1100 Top View Rear Section	V-7
5-3	Schematic Diagram D.C. Servo	V-8
5-4	GCU-1100 Schematic Diagram	V-9

LIST OF TABLES

TABL	E	PAGE
3-1	35 Foot Whip Antenna	III-4
3-2	75 Foot Long Wire Antenna	III-5
3-3	150 Ft. Sloping Long Wire Antenna	III-7
3-4	RF Capacitor Current Rating Data	III-9
5-1	Wire List	V-8

SECTION 1

GENERAL INFORMATION

1.1 Purpose of Instruction Book:

This instruction book describes the GCU-1100 Kilowatt Antenna Coupler and includes installation details, tuning instructions, operating instructions, and maintenance procedures. Information in this instruction manual applies to all equipment configurations unless otherwise stated in the text or illustrations.

1.1.1 Purpose of Equipment:

The purpose of the GCU-1100 Antenna Coupler is to match the 50 ohm nominal output impedance of an associated power amplifier to the input impedances of a 35 foot vertical or 75 & 150 foot long wire antennas over the frequency range of 1.6 to 30 Mhz. Power capability is 1000 watts PEP or Average. The GCU-1100 has ten pre-set channels. The channel selector switching function is normally controlled by a master switch wafer in the power amplifier. The antenna coupler is intended for continuous duty, unattended operation in fixed station ground radio communications systems.

1.2 Equipment Description:

Outline and mounting dimensions for the GCU-1100 are shown on the Outline drawing, Figure 2-1.

The antenna coupler consists of a basic "Pi" network with RF switching circuits used to select input and output capacitors as needed. The RF network inductor is a motor driven variable type and is controlled by a resistor bridge position servo system. The entire RF network and control circuits are contained in an enclosure constructed entirely of aluminum to provide the best possible conduction of heat generated in the RF network, from the unit. An access cover with gasket material and compression-type fasteners is used to provide splash-proof construction.

1.3 Electrical Specifications:

Power Capability

1000 watts PEP or Ave.

Antenna Matching Capability

35 foot vertical, 75 foot or 150 foot long wire.

Frequency Range

1.6 to 30 Mhz.

Duty Cycle

Continuous

Number of Channels

Ten (pre-set)

Channel Switching Time

Ten seconds maximum

Input Impedance

50 ohms nominal

Environmental:

Ambient Temperature

 -30° C. to $+50^{\circ}$ C.

Humidity

To 95% R. H.

Altitude

To 5000 feet above sea

level

Shock & Vibration

As encountered in normal

handling and shipping

Dimensions

30" high x 22" wide x

12" deep

 $(76 \times 56 \times 31 \text{ cm})$

Weight

73 lbs (33 kilograms)

1.4 Equipment Supplied:

Kilowatt Antenna	Coupler, Type	GCU-1100
with control con	ector (plug)	

Part Number

5026-0000

1.5 Equipment Required, Not Supplied:

1. Transceiver, GSB-300, 115/230 VAC

97892

2. Coaxial Cable,

58864

		Part Number
	3. GSL-1000 Linear Power Amp	6026-0000
	4. Coaxial Connectors, (2 reqd)	74219
	5. GSB-300/GSL-1000 Interface Cables	98023
	6. GCU-1100 Control Cable	58878
	7. Antenna, Fixed:	
	35 foot vertical	71585
	or 75 foot long wire kit	99920
	or 150 foot long wire kit	99921
1.6	Optional Equipment:	
	Caster Set (4), for GSL-1000	98014
	GSL-1000 Running Spare Parts Kit	98015
	GSL-1000 Depot Spare Parts Kit	98016
	GCU-1100 Depot Spare Parts Kit	98017
	GCU-1100 Running Spare Parts Kit	99414
	R-20 Reflectometer	97847

		ţ

SECTION 2

INSTALLATION

2.1 Unpacking and Inspection of Equipment:

The GCU-1100 antenna coupler is packed in a crate using sturdy construction. The crating and packing material should be removed carefully and the contents inspected for physical damage. Any resulting claims for shipping damage should be filed promptly with the transportation company. If it is found necessary to file such a claim, retain all packing material.

Do not accept a shipment where there are visible signs of damage to the shipping container until a complete inspection is made. If there is a shortage, or evidence of damage is noted, insist on a notation to that effect on the shipping papers before signing the receipt from the carrier.

A full report should also be forwarded to Sunair.

Include the following:

- 1. Order Number
- 2. Model and Serial Number
- 3. Name of Transportation Agency

When this information is received by Sunair, arrangements will be made for repair or replacement.

2.2 Return of Equipment to Sunair:

The shipping crate for the GCU-1100 has been carefully designed to protect the equipment during shipment. The container and its associated packing materials should be used to reship the unit.

When returning sub-assemblies or components for repair or replacement, be sure to pack each unit separately, using suitable cushioning material where necessary.

Shipment should be AIR PARCEL POST consigned to:

SUNAIR ELECTRONICS, INC.
3101 SW THIRD AVENUE
FORT LAUDERDALE, FLORIDA 33315
U.S.A.

Plainly mark all mailing documents with indelible ink as follows:

U.S. GOODS RETURNED FOR REPAIR VALUE FOR CUSTOMS - \$100.00

Mark all sides of the package:

FRAGILE - ELECTRONIC EQUIPMENT

2.3 Installation Procedure:

The satisfactory operation of the equipment will depend on the care and thoroughness taken during the installation phase.

2.3.1 General Installation Requirements:

- 1. Carefully plan transmitter/coupler/antenna locations, observing the following requirements before starting installation work.
- 2. Provide the best possible RF ground for the system. Use flat copper strap at least 1" wide or #6 or larger copper wire and make connections to the ground terminal of all system components. Keep all ground leads direct and as short as possible. After the system grounds have been installed, connect the station ground system to the antenna coupler ground terminal. Bear in mind that the antenna ground lead is actually part of the antenna itself, and therefore will have a marked effect on the antenna input impedance. If a 35 foot vertical antenna is to be used, at least 12 separate 35 foot radials connected to a common ground stake, are recommended.
- 3. Provide the maximum possible separation between the coupler/antenna and the associated radio transmitter. 100 feet is the recommended minimum distance and up to 250 feet separation may be used.
- 4. The antenna lead from the antenna coupler RF output insulator must be insulated for at least 15kv potential. As an alternative, copper tubing with an outside diameter of at least 1/4" may be used, provided that it is routed to the antenna terminal

metal objects in its vicinity. It is important to keep the length of this lead to an absolute minimum since it forms a part of the radiating portion of the antenna. Three (3) feet would be the maximum distance if antenna efficiency is not to be compromised.

5. Linear amplifiers with low level modulation such as is used in the GSB-300 will sometimes oscillate if the high level RF output is radiated or conducted into the low level stages. Evidence of this situation is erratic or excessive power output. This is caused by too close proximity of the antenna to the transceiver and/or a poor RF ground system. Carefully following the above procedures will prevent this problem.

2.3.2 Mounting Considerations:

Refer to Figure 2-1 for coupler outline configuration.

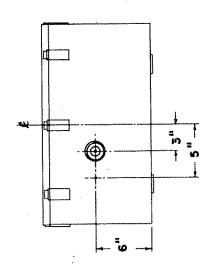
The intended mounting position for the GCU-1100 is in the vertical plane with the high voltage antenna insulator at the top. The enclosure may also be mounted in the horizontal position, but will require that the control and coaxial connectors be sealed with a suitable compound such as Dow-Corning DC-5, to prevent water entrance.

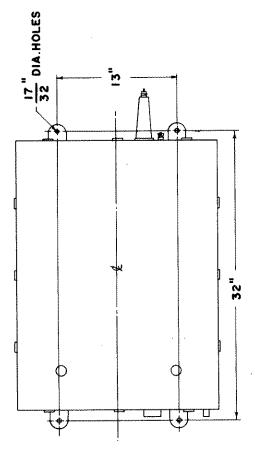
Four mounting feet with 1/2 inch diameter holes are provided on the back of the enclosure. If it is necessary to mount the coupler on a wooden pole, simple angle-iron adapter brackets may easily be fabricated. Since the total weight of the unit is only 73 pounds, two wooden 4x4's set in cement would provide dependable support.

2.3.3 Installation of Remote Control & RF Cables:

It is recommended that the remote control cable be procured from Sunair. However, if necessary, the cable may be made from individual No. 16 AWG stranded wire with an overall braided shield and PVC jacket.

Inter-connection cable details are given on Figure 2-2.





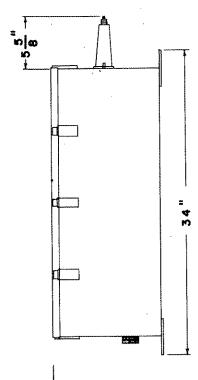
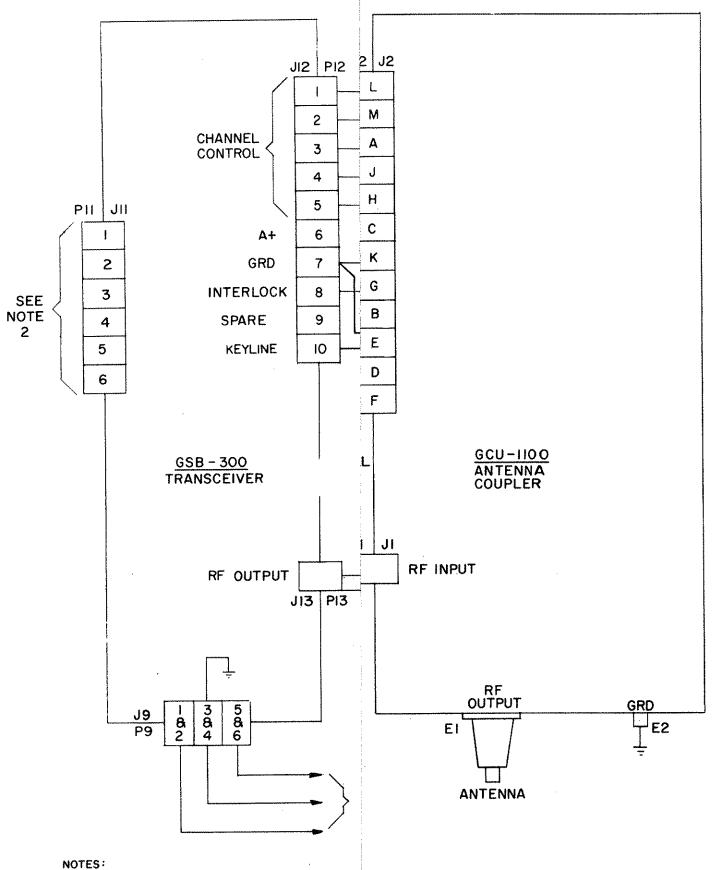


FIGURE 2 - I

OUTLINE CONFIGURATION ANTENNA COUPLER



1.115 VAC-JUMPER 2TBI-1 TO 2TBI-2 & 2TBI-3 230 VAC-JUMPER 2TBI-2 TO 2TBI-3. 2. AUDIO CONNECTIONS, SEE GSB-300 INST.BOO

3. TEN FEET OF 3 COND. NO. 10 AWG FURNISHED WUSE NO. 8 AWG FOR RUNS LONGER THAN 10 FE 4. ALL CONNECTORS EXCEPT COAXIAL TYPES FWITH EQUIPMENT.

SYSTEM INTERCONNECT DIAGRAM FIGURE 2-2

> 11-4A 1100

.

2.4 Preliminary Electrical Checks:

When the system installation has been completed, perform the following checks:

- 1. Temporarily remove the top cover and inner RF shield plate from the coupler.
- 2. Connect a 50 ohm, 100 watt dummy load to the RF output connector of the associated exciter.
- Turn on the filament voltage supply on the GSL-1000.
 The coupler cooling fan should be energized.
- 4. Manually turn the variable inductor two turns. Press the servo activate switch on the potentiometer bracket in the coupler, hold the switch button down until the servo motor has returned the inductor to its original position and stopped.
- 5. Turn the exciter channel selector switch to a different channel. Note that the servo system is energized and the motor runs to a new position. Check for proper operation on all assigned channels.
- 6. Switch the coupler safety keyline interlock toggle switch to the "off" position. Turn on the GSB-300 exciter and insure that it cannot be keyed with the coupler interlock switch in the "off" position.
- 7. Turn off all equipment and replace all covers.
- 8. Proceed to Section III and follow the tuning procedure given therein to complete the system check out.

NOTE

It is not possible to tune the antenna coupler at the factory as each antenna installation is different. Therefore it is mandatory that each active channel in the coupler be tuned after installation by following the procedure contained in Section III.

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SECTION 3 OPERATION

3.1 Test Equipment Required:

- 1. RF Wattmeter, Bird Thruline, Model 43 with 100 and 1000 watt, 2-30 mhz, 50 ohm, elements.
- Audio Frequency Generator, Hewlett-Packard Model 206A or equivalent.
- 3. VOM, Triplett Model 630 or equivalent.
- 4. Short length of RG-8A/U coaxial cable with UHF Plug (PL-259) on one end and plug to mate with Bird wattmeter "QC" connector on the other. 2 required.
- 5. Adapter, UHF, Type PL-258
- 3.2 RF Network Final Adjustment, Preliminary:

It is assumed that the GCU-1100 has been installed according to the instructions given in Section II.

The RF network component values for the 35 ft. vertical, and 75 & 150 ft. long wire antennas are given in Tables 3-1, 3-2, & 3-3. Capacitor ratings are listed on Table 3-4.

Insure that the correct input & output padder capacitors have been installed for each channel frequency as listed in the tables. The actual antenna impedance may vary considerably from these values because of differences in ground paths and the height of the support structures.

Temporarily connect the audio generator to the GSB-300 audio jack, J11-1&2. Do not ground either lead. In addition, connect a SPST switch to J11-5 & 6 to serve as a temporary key.

Connect the wattmeter at the coupler RF input so that it may easily be observed while making adjustments. Install the interior RF shield cover over the RF network.

3.3 RF Network, Tuning Procedure:

 Locate the adjustment potentiometer for the channel in use by counting from the righthand side of the control board. The potentiometer on the extreme right is channel one. (The wire to the terminal board, TB-1, is also color

- coded according to its channel number. The terminal may be followed to the potentiometer as a check).
- 2. The variable inductor provides approximately 0.8 microhenries per coil turn. Using the data provided in the tables, set the inductor to its approximate inductance. Press the servo activate switch button and adjust the command potentiometer until the inductor is near its tabulated setting.
- 3. Place the GCU-1100 keyline interlock switch in the "On" position.
- 4. Turn on the GSB-300 and the GSL-1000 filament and plate voltage.
- 5. Place the GSB-300 Mode switch in the USB or LSB position. Insure that the audio generator gain control is set at minimum. Select the channel to be adjusted.
- 6. Close the key and advance the audio input level until 10 or 15 watts reflected power is indicated on the GSL-1000 test meter. Switch to forward power and note the RF output level. If the forward power is 100 watts or more, the coupler network will require very little adjustment.
- 7. Move to the coupler location and open the coupler keyline interlock switch. Loosen the channel tuning capacitor locknut, (7/16"). Key the system and adjust the variable capacitor and inductor for minimum reflected power on the wattmeter. Tune each variable element in turn and repeat the process several times. It should be possible to obtain zero or nearly zero reflected power for all antennas and channel frequencies.
- 8. If the procedure in step 7 does not produce a null, more output padder capacity is required if the variable inductor is attempting to tune at maximum, and/or more input capacity is required if the input variable capacitor is at maximum, or less if at minimum. In general, use the lowest value of output capacity possible for best tuning efficiency.

- 9. Adjust the input audio to produce an output level of approximately 500 watts if voice operation is intended or 1000 watts for CW and AFSK. Allow the system to run for ten or fifteen minutes, then recheck reflected power. Touch up the coupler tuning, if necessary. Usually this minor adjustment can be made with the variable input capacitor. Tighten the lock nut and recheck.
- 10. Repeat the above procedure for each active transmit channel.

NOTE

When tuning the coupler network to channel frequencies that require small values of inductance, allow at least one full turn for overshoot travel. The minimum inductance requirement can be adjusted by changing the output capacity value.

CAUTION

The data which follows for the three major antenna types, is intended FOR USE AS A GUIDE IN SELECTING APPROXIMATE NETWORK VALUES. The data reflects exact values for matching the tabulated antenna impedances to 50 ohms. Circuit strays and the actual antenna configuration could have a marked effect on the final values needed. Since the output capacitor is a fixed value, USE THE NEAREST AVAILABLE STANDARD CAPACITY with the necessary current rating as listed in the tables.

35 FOOT W	35 FOOT WHIP ANTENNA	SHAKES 12 EA	PEARE STYLE 35' RADIALS	SHAKESPEARE STYLE 222 3%" BASE DIA. 12 EA - 35' RADIALS & 8' GRD ROD, SANDY SOIL.	ASE DIA.					
FREO (KHZ)	IMPEDANCE	C1(PF)	#n)	C2(PF)	IC1(A)	IL(A)	Ic2(A)	Loss(w)	EANT(V)	ANT(A)
1600			-							
2000	5 — j600	9211	20.0	194	25.8	26.2	15.6	432.4	6603	10.6
3000	7 — j365	3338	15.1	20	14.0	14.7	3.8	154.5	3979	10.9
4000	10 — j245	2086	8.1	20	11.7	12.5	3.0	79.7	2329	9.5
2000	20 — j145	1041	4.4	20	7.3	8.5	9.	25.4	1010	6.9
0009	30 – j55	536	2.0	20	4.5	6.3	0.7	7.5	357	5.7
7000	50 + 125	16	9.0	365	0.1	4.4	4.0	1.3	246	4.4
0008	80 + j100	21	1.7	293	0.2	4,4	6.7	4.3	448	3.5
0006	135 + j180	28	2.3	184	0.3	4.4	6.4	6.3	209	2.7
10MHZ	225 + j270	21	2.5	127	0.2	4.4	5.9	7.7	738	2.1
11.0	410 + j370	36	2.7	91	0.5	4.5	5.3	9.6	828	1.5
12.0	775 + j250	30	2.7	89	0.5	4.5	4.6	10.3	968	=
13.0	900 — j260	25	2.6	5	0.4	4.4	4.0	10.5	937	1.0
14.0	465 — j470	151	2.2	20	2.9	5.3	4.1	13.9	926	4.1
15.0	250 — j400	203	2.8	20	4.2	6.1	4.3	16.1	968	6.
16.0	125 — j255	219	4.	20	4.9	9.9	4.0	15.5	795	2.8
17.0	85 — j175	213	<u></u>	20	5.0	6.7	3.6	13.5	661	3.4
18.0	65 — j105	180	0.8	20	4.5	6.3	2.8	9.5	482	3.9
19.0	60 – j62	136	9.0	20	3.6	5.7	2.1	6.2	345	4.0
20.0	65 + j25	4	0.3	117	0.4	4.4	4.0	1.9	271	3.9
22.0	110 + j14	7	0.4	8	0.4	4.4	3.8	2.9	333	3.0
24.0	250 + j250	25	ō.	54	0.8	4.5	5.5	7.9	672	<u>6.</u>
26.0	545 + j140	109	6.0	20	3.9	5.9	0.9	12.8	732	1.3
28.0	450 + j240	151	0.7	20	5.9	7.4	0.9	16.9	714	4.
30.0	135 — j165	149	0.5	20	6.2	7.7	5.5	14.2	276	2.7

75 FOOT L	75 FOOT LONG WIRE ANTENNA							Ø	SHEET 1 OF 2
FREQ (KHZ)	IMPEDANCE	C1(PF)	^L (UH)	C2(PF)	I,C1(A)	IL(A)	IC2(A)	Lant(a)	EANT(V)
1600	100 – 515	3012	22.5	299	6.8	14	4.9	3.1	1626
2000	75 — j352	715	22.5	77	2.1	5.3	د.	3.6	1295
2500	78 – j181	87	9.7	84	4.	4.4	0.1	3.5	069
3000	82 – j53	40	3.1	234	.2	4.4	ر ن	3.4	331
3175	74 + j0	31	1.8	470	.2	4.4	2.5	3.6	266
3500	84 + j93	24	3.8	672	.2	4.4	6.3	3.4	426
4000	108 + j203	35	5.9	394	2.	4.4	6.9	ო	689
2000	352 + j823	92	10.7	127	.7	4.5	5.8	1.6	1432
5700	2900 + j0	51	10.6	73	rvi	4.5	3.8	ឃុំ	1450
0009	2300 – j1030	67	9.8	29	œ.	4.5	3.9	œί	1512
7000	222 — j685	3,7	6.8	20	.s.	6.5	3.4	2.1	1512
8000	160 – j300	44	3.7	20	က်	4.5	2.2	2.5	850
0006	110 – j77	27	1.3	88	₹,	4.4	2.1	က	402
9380	110 + j0	ស	6.	169	-	4.4	3.3	က	330
10MHZ	130 + j145	17	1.7	181	ωi	4.4	ပ	2.7	525
11.00	250 + j490	53	3.5	82	o;	4.6	6.3	2	1100
12.00	1210 + j700	30	3.7	5	9.	4.5	4.9	oi.	1258
12.38	1700 + j0	144	3.5	20	2.6	5.8	4.7	7.	1190
13.00	675 — j565	150	2.7	20	2.8	9	4.4	1.2	1056
14.00	482 – j465	149	2.2	20	ო	6.3	4.2	1.4	937
15.00	163 — j209	133	1.5	20	2.8	6.1	က	2.4	929
15.85	170 + j0	8	αi	92	4.	4.5	3.8	2.4	407
16.00	152 + j50	21	φ	-	rvi	4.5	4.5	2.5	400
17.00	259 + j278	24	1.5	72	φ.	4.5	5.6	0.1	721
18.00	717 + j668	146	0.	20	3.7	7.4	6.1	-	1077
18.60	1600 + j0	227	1.6	20	9	11.9	9.9	.7	1119
19.00	1030 — j74.7	253	1.4	50	6.8	13.9	6.9	o.	1145
20.00	265 — j424	228	****	20	6.5	13.1	9	<u>0.</u>	950
	**************************************	***************************************	***************************************	***************************************			***************************************		

¥	180 – j187 170 – j42 165 + j0 204 + j127 348 + j373	C1(PF) 134 8 7	•						
E	180 – j187 170 – j42 165 + j0 204 + j127 348 + j373	134 8 7	*****	C2(DE)	IC1(A)	I,L(A)	IC2(A)	LANT(A)	EANT(V)
•	180 – j187 170 – j42 165 + j0 204 + j127 348 + j373	134	(OH)	C.L.	70	7.8	4.0	2.3	296
	170 – j42 165 + j0 204 + j127 348 + j373	2 8	ნ.0	OC II)	4 4	3.2	2.4	480
	165 + j0 204 + j127 348 + j373		Ö r	င္ပင	j u	. 4	3.7	2.4	395
	204 + j127 348 + j373		ဂ ၊	00	500	4.4	5.2	2.2	528
	348 + j373		•	0 0	2.7	6.4	6.2	1.6	816
	-	06		06 1	- o	14.1	7.8	o.	981
	1080 + j153	195	ວາ. ເ) () r	147	7.9	o.	686
	1100 + j0	199	တ	ລດ		, c	6.7	<u>1.</u>	818
	522 - j352	<u>~</u>	αį	20	0.7	2 0	, C	17	612
· ·	315 – 1175	124	7:	20	. 2	7. 1	, 4	0	522
.	07E + iO	56	ø.	20	2.3	ဂ ဂ	0,4	<u> </u>	5.47
.	27.3 1.30	78	ψ	20	2	5.2	Ω	o. •	7
O. (286 + J105) +	7.	20	4.7	9.1	7.3	o.	0
o.	3/0 + 5/25								
·		(ď	4	0		4.0		

EANT(V)	391	333	591	1340	2000	1698	1186	350	378	632	1399	1329	406	364	892	1119	1266	528	364	909	1039	804	375	475	1099	1079	1031	402	910	066
TANT(A)	င	2.9	2.7	2	ιυ	7.7	2.7	2.8	2.7	<u>r</u> .	7.	1.9	2.8	2.7	0.			2.4	2.7	2.8	αi	2.3	2.5	2.5	1.0	တဲ့	1.9	2.3	1.4	တ
IC2(A)	2	3.4	6.3	6.2	4.9	2.7	<u>0.</u>	3.5	4.7	4.4	4.4	က	2.4	3.6	5.0	4	4	2.3	3.6	5.7	4.3	3.6	3.6	5.4	5.6	က က	5.6	3.7	5.5	တ်
IL(A)	4.4	4.4	4.4	4.4	4.8	4.5	4.4	4.4	4,4	4.4	4.4	4.9	4.4	4.4	4.4	4.5	4.9	4.4	4.4	4.4	4.7	5.6	4.4	4.5	5.2	5.6	7.2	4.4	6.5	6.4
Ic1(A)	0.1	.2	7.	.2	2	œ	ঘ.	ωi	.2	က	ιυ	2.3	₹.	က	က	۲.	2.2	.2	m.	4	9.	3.6	ιĊ	ō.	2.8	3.5	5.8	w	4.8	oj.
C2(PF)	499	963	838	290	129	70	224	224	391	181	78	20	115	188	115	58	20	63	134	123	20	20	103	120	20	20	20	80	20	20
£ (UH)	7.3	5.6	0	19.7	22.5	18.2	10.5	2	2.3	3.7	7.8	6.7	7.5	1.3	3.5	4.6	4.4	1.6	oj.	1.7	က	1.8	ωi	1.0	2.3	2.1	7.5	7.	1.3	1.5
C1 (PF)	O		50	40	469	5	5	32	81	29	47	224	32	24	24	28	154		91	0	98	179	24	26	120	152	241	œ	177	172
IMPEDANCE	108 – j73	115 + j0	132 + j175	229 + j630	4000 + j0	310 j950	136 – j418	125 + j0	128 + j57	416 + j68	2000 + j0	251 — j653	126 – j72	135 + j0	262 + j390	1600 + j0	785 — j842	161 — j150	135 + j0	199 + j191	1300 + j0	185 – j297	150 + j0	156 + j109	952 + j550	1200 + j0	272 - j470	175 + j0,	498 — j418	1100 + j0
FREQ (KHZ)	1600	1640	2000	2500	3000	3500	4000	4900	2000	0009	6400	7000	8000	8200	0006	9700	10(MHZ)	11.0	11.5	12.0	13.0	14.0	14.7	15.0	16.0	16.2	17.0	18.0	19.0	19.5

SHEET 1 OF 2

:]

150 FOOT SLOPING LONG WIRE ANTENNA

150 FOOT 8	150 FOOT SLOPING LONG WIRE ANTENNA	NTENNA						S	SHEET 2 OF 2
FREG	IMPEDANCE	C1 (PF)	L(UH)	C2(PF)	IC1(A)	IL(A)	(K2(A)	TANT(A)	EANT(V)
20.0	482 – 1535	221	1.2	50	6.3	7.6	6.4	4.	1008
21.0	174 – j126	98	œ	50	2.7	5.1	3.3	2.3	494
21.3	190 + 10	6	9:	99	ri,	4.4	3.7	2.2	418
22.0	328 + 1230	27		55	o.	4.5	5.2	1.7	681
22.0	0! + 006	162	-	50	5.2	6.8	6.4	1.0	006
23.0	693 — 1400	190	0.	20	6.2	7.6	7	1.2	096
24.0	150 – 1150	129	۲.	50	4.4	6.2	4	2.5	230
2,42 R	185 + 10	/	က်	58	4.	4.4	3.8	2.3	425
24.5 2F.0	234 + 1135	<u></u>	<u></u>	59	7:	4.5	က်	7	540
25.0	00 + 008	: [2	ω.	50		7.3	7.2	f 11	879
27.0	206 - j3 206 - j245	60	φ.	20	2.2	7.7	ဖ	2.2	704
27.0	130 + i0	LC	, α	56	2.7	4.4	3.5	2.7	351
20.00	193 + 187	12	កប់	28	2.2	4.4	4.8	2.2	461
20.0	555 + 1272	135	·-	20	5.5	7.0	7.4	£.	803
20.2	1.75 · 600 0: + 008	170	۲:	20	7.1	8.3	8.1	<u></u>	880
30.0	260 - 1280	174	က်	20	7.4	8.5		<u>6.</u>	738
30.0 0	202								

TABLE 3-4
RF Capacitor Current Ratings

Carain	Conceitor	1701+ngo	Current
Sunair	Capacitor	Voltage	
P/N	Type/value	Rating	Rating
27545	Ceramic,NPO,25pf (type 857)	15kv	6.2 amps
27546	Ceramic,NPO,50pf (type 857)	15kv	7.4 amps
29032	Ceramic,NPO,25pf (type 850)	5kv	3.1 amps
29020	Ceramic,NPO,50pf (type 850)	5kv	4.2 amps
27550	Mica, 220pf	2.5kv	1.8 amps
28204	Mica, 470pf	2.5kv	3.1 amps
27548	Mica, 1000pf	2.5kv	4.0 amps

The current ratings listed above should not be exceeded when these capacitors are connected in parallel. Refer to the data given in Tables 3-1, 3-2 & 3-3 for typical values.

SECTION 4

THEORY OF OPERATION

4.1 Antenna Tuning Network:

4.1.1 General:

The antenna tuning network consists of a conventional "Pi" network to permit matching antennas with a wide range of impedances to the required 50 ohms. The tuning network consists of three elements, 1. input shunt capacitance, 2. series inductance, 3. output shunt capacitance.

4.1.2 Input Shunt Capacitance:

The input branch of the "Pi" network consists of a two section air variable capacitor, one capacitor for each channel (total ten). Each section is 380 pf or 760 pf total. If the antenna impedance at the channel frequency is found to require more capacity, high voltage mica padders are connected by a ceramic switch wafer, S2C. A second wafer, S2D is used to connect the air variables.

4.1.3 Series Inductance:

The variable inductor, Ll, forms the series leg of the "Pi" network. The range of this inductor is nominally 0.2 to 22.5 microhenries. The high unloaded Q of this inductor (typically 200), and its high current handling capacity contributes to the high efficiency of the antenna coupler. The inductor is positioned by a servo system. A switch wafer, S2B, is controlled by the channel selector solenoid, B2. The switch section is used to connect a ten turn potentiometer across the motor follow potentiometer, R21. A floating reference supply voltage is connected across the potentiometers, and their wipers are connected to the servo amplifier signal input The resistor bridge circuits are used to terminals. position the inductor as required. A separate potentiometer is used for each of the ten available channels. A mechanical back turns shorting device is actuated by the contact assembly as it travels down the inductor coil turns. The shorting device is necessary to remove the back turn (shorted turns) resonance from the operating

frequency when only a few inductor turns are active.

4.1.4 Output Shunt Capacitance:

The output shunt branch of the network is composed of banks of high voltage ceramic capacitors connected as needed and selected according to channel requirements by the high voltage switch section, S2E.

4.2 RF Circuit Efficiency:

The efficiency, (the ratio of power output to power input) of the antenna coupler is strongly dependent on the reactive circulating current through the series inductor, Ll, and on the quality factor (Q), of this element. The circulating current, in turn, is dependent on the value of the output capacity in the circuit. The output capacity, in this application of a "Pi" network is used to transform the antenna impedance to a value that is within the range of the tuning network. The network can therefore be considered to be a basic "L" network preceded by an impedance matching capacitor. In the GCU-1100, therefore as with all wide range antenna couplers, a good impedance match may always be obtained with high values of output capacitance, however it is important that the operator follow the recommended tuning procedure and search for an impedance match at the lowest possible value of output capacity, in order to transfer maximum power to the antenna.

4.3 Control Circuits:

The rotary solenoid channeling pulse is used to initiate a tune sequence. When the solenoid is channeled, a sample of its ground pulse is applied to the unijunction timer circuit Q1/Q3 through the gating diode, CR4. The purpose of this timer is to allow the rotary solenoid to complete its channeling sequence before the servo system is activated. The timer is set for approximately 3 seconds. The 3 second timer relay contacts are used to charge a capacitor, C31, during the hold-in period. When the timer releases, the capacitor discharges into the emmiter of Q2 which starts the second timer, Q2/Q4 and its relay, K2. This timer is used to activate the servo amplifier so that the variable inductor can move to a new position. In addition, a set of contacts on K2 are used to open the system keyline to insure that RF drive is not applied while the servo system is operating. A

second function is served by this timer, it insures that the servo motor is not left energized for long periods of time, in the event of a failure in the potentiometer bridge circuit, which would cause the motor to run to a mechanical limit stop and stall. The timing period is approximately ten seconds.

4.4 Series Inductor Position Servo System:

Refer to the simplified schematic, Figure 4-1.

The servo system used in the GCU-1100 antenna coupler is a conventional resistor-bridge position servo with D.C. components throughout. Ten channel adjustment potentiometers are used in the bridge circuit, one for each channel. channel selector switch section, S2B, connects the wiper of the operational potentiometer to the servo amplifier signal input. When the servo amplifier is enabled, the bridge circuit will supply a positive or negative error signal depending on the relative settings of the command pot. R13, (channel 3 is shown as the active position on Figure 4-1), and the servo motor follow pot., R21. servo motor polarity and direction of rotation is connected so that when the follow pot. has been positioned to the same relative setting as the command pot. the D.C. bridge will be balanced, and the input signal to the servo amplifier is The command pot. is a ten-turn screwdriver adjust type. The follow pot. is also a ten-turn device, but it is geared to the motor output shaft so that when the command pot. is adjusted over its complete range, the inductor will travel from its maximum to minimum inductance limits. The bridge circuit uses a "floating" reference voltage, (33 VDC).

4.5 Servo Amplifier:

Refer to the simplified schematic, Figure 4-2.

The servo amplifier in the GCU-1100 is a solid-state, direct-coupled circuit with a bridge connected power output stage. Over-all feedback is used to reduce off-set drift and improve operation at low levels.

Refer to the D.C. Servo Amplifier schematic diagram, \$5026-0011.

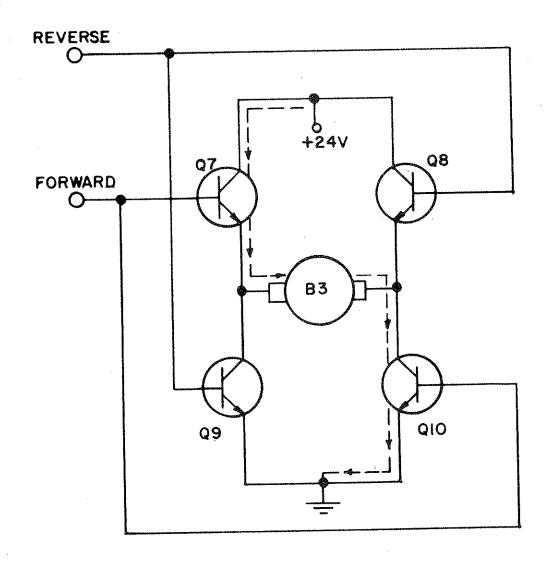


FIGURE 4-2
GSU-1100
SERVO AMPLIFIER
OUTPUT BRIDGE
SIMPLIFIED

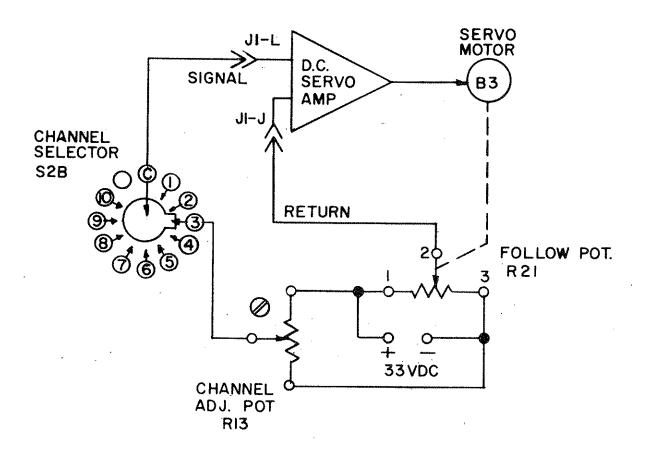


FIGURE 4-1
GCU-1100
INDUCTOR POSITION
SERVO SYSTEM
SIMPLIFIED

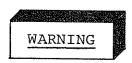
The amplifier is a combination printed circuit and hard wired assembly with integral heat-sink. The input stage is an operational amplifier, AR1, to provide a high input impedance to the error signal. Diodes, CR1 & CR2 are connected back-to-back across the input to avoid saturating and possible latch-up at large input signal levels. output of the op-amp is coupled directly to positive and negative level sensors, Q2 & Q3. The servo enable transistor, Ql is also connected to the same point. Ql is normally in the conducting state because of the positive base bias supplied by the zener diode, VR1. When the enable input is grounded, (J1-F), Q1 is shut off, resulting in a high impedance at the op-amp output junction. Either Q2 or Q3 will then conduct, depending on the polarity of the output signal. The positive error sensor, Q2 is coupled directly to the positive driver amplifier, Q5, while the negative error sensor is coupled to its driver, Q6 through an inverter stage Q4. The purpose of the inverter is to obtain symetrical operation in the bridge power amplifier stage.

The output amplifier connections are shown in a simplified form on Figure 4-2. Assume that a positive error signal is being amplified. Driver transistor, Q5 conducts, turning on the bridge pair, Q7/Q10. The dashed lines on the simplified schematic show the current path through the servo motor which results. A negative input will turn on the amplifier pair, Q8/Q9, reversing the current path through the motor. The servo motor is a D.C. permanent magnet type, which provides bi-directional rotation when the applied voltage across it is reversed in polarity.

In the GCU-1100 antenna coupler servo system, the two inputs labeled "+Forcing" & "-Forcing", (J1-E & N) are not used.

SECTION 5 MAINTENANCE AND REPAIR

5.1 Periodic Maintenance:



OPERATION OF THIS EQUIPMENT INVOLVES THE USE OF HIGH VOLTAGES (15kv peak under some conditions) WHICH ARE DANGEROUS TO LIFE. OBSERVE SAFETY REGULATIONS AT ALL TIMES. DO NOT MAKE ADJUST-MENTS INSIDE THE EQUIPMENT WITH HIGH POWER ON. DO NOT DEPEND ON THE KEYLINE INTERLOCK FOR PROTECTION. TO AVOID INJURY ALWAYS GROUND CIRCUITS BEFORE TOUCHING THEM. DO NOT SERVICE ALONE.

In the normal service life of any piece of equipment, faults and breakdowns will develop. In order that necessary repairs may be carried out in a reasonably short time, a logical test routine must be followed. The maintenance technician should familiarize himself with the circuitry and the physical layout of the equipment prior to the occurrence of trouble.

When repairs are necessary, it is recommended that this servicing be done whenever possible by competent radio technicians, supplied with suitable tools and test equipment.

In order to assure continued trouble-free operation from the GCU-1100 antenna coupler, the following periodic maintenance should be performed every 3 months (monthly, if operated in a salt atmosphere such as a coastal base station).

- 1. Remove the cover from the coupler enclosure.
- Inspect the synthetic rubber gasket material for signs of deterioration and stickiness. Lubricate if necessary with Dow Corning 4X silicone lubricant. (Sunair P/N 85854).
- 3. Check all hardware and retorque, if necessary.
- 4. Apply a small amount of the Dow Corning 4X lubricant to the mechanical limit stop washers, use the PVC tubing extension for the spray nozzle (furnished with the spray can).

- 5. Check the servo drive timing belt tension and adjust if necessary. (Press belt at center of its span with one finger, it should not be possible to deflect the belt more than 1/16 of an inch when exerting moderate pressure). Finally, manually move the inductor 5 or 6 turns off its normal position and activate servo. Insure that no slippage occurs when motor starts and/or reverses.
- 6. Apply a small amount of molybdenum grease to the variable inductor slide support bar. (Dow Corning "Molykote" Type G, Sunair P/N 84095). Wipe off all excess grease after running the inductor over its normal range several times. Note: Do not apply the grease to the insulating material, clean these surfaces, if necessary with a non-toxic solvent such as Trichloroethane.

5.2 Troubleshooting & Repair:

5.2.1 Required Test Equipment:

- 1. VOM Triplett Model 630 or equivalent
- 2. RF Wattmeter, Bird Thruline Model 43 with 100 and 1000 watt, 2-30 Mhz elements. (50 ohms).
- 3. Audio Frequency Generator, Hewlett-Packard Model 206A or equivalent.
- 4. Coaxial cables, misc. short lengths to permit connection of wattmeter ahead of GCU-1100 RF input jack. Coaxial fittings for cable to mate with wattmeter & UHF type coupler connector.

5.2.2 Timing Period Adjustments:

Connect an ohmmeter to the tune control board, PCl-TBl, terminals 18 & 19. The ohmmeter will indicate the status of relay K2, continuity will indicate that the relay is unenergized. Connect a short jumper (clip lead type) to PCl-TBl-14 (dc common). Now touch the other end of the clip lead to CR4 (anode) momentarily. The time span from the instant the terminal is touched until the ohmmeter indicates an open circuit, (K2 energized) should be approximately 3 seconds. If it is not, adjust PCl-R4 until the correct timing period is found.

The second timer controls K2, which in turn, enables the servo amplifier, and opens the keyline interlock circuit. The timing period should be on the order of 6 seconds (to permit the inductor to be positioned as needed). The adjustment is made with R8.

NOTE: The DC ground for all power supplies is kept isolated throughout the coupler. Do not attempt to measure the servo amplifier output voltage, (motor voltage) with a grounded type instrument such as an oscilloscope. This will short circuit the output bridge network.

5.2.3 Voltage Measurements, Tune Control Board, PC1:

All measurements made to DC common, PCl-TBl-14, with VOM (20,000 ohms/volt).

PC1-TB-1		
2		
3		
4	Terminal	s 1-10
5	0 to 33	volts, depending on control
6	pot. set	tings. Channel selected will
7	read 0 v	olts at null.
8		
9		
10_		
11	28 volts	
12	-5 volts	
13	24 volts	N.C. indicates no
14	0	connection (external)
15	2.65 volts	
16	18 volts	
17	18 volts	
18	N.C.	
19	N.C.	
20	-12 volts	
21	0	

5.2.4 Voltage Measurements, Servo Amplifier Board:

All measurements made to DC common, J1-R with VOM.

```
J1-A
      42 volts
      42 volts
   В
   C
   D
       0
   E
      N.C.
   F
      2.65 volts
      11.5 volts
   Η
   J
   K
        0
   M -11.8 volts
   N
      N.C.
   P
        Λ
        0
   R
   S
   ጥ
   U
        0
   v
```

5.2.5 Servo Amplifier Check:

If the servo system is operational, select a channel which places the inductor slider near the middle of its normal travel. If the amplifier is defective, (motor will not run when channel is changed), connect a voltmeter on a low voltage range from J1-J to J1-L, switch polarity as necessary. Now turn the inductor manually until the voltmeter indicates 0 volts.

Connect the voltmeter positive lead to J1-U or V, negative lead to J1-C or D. Manually turn the inductor 3 full turns toward the output end of the coil. Hold the inductor firmly with one hand and press the servo activate switch with the other. The meter should indicate approximately 12 volts.

Return the inductor to its original position, reverse the voltmeter leads and repeat the measurement while the coil is 3 turns in the other direction. As before, the meter should indicate 12 volts.

5.2.6 Spark Gap Adjustment:

The spark gap at the output of the coupler should be set for a nominal spacing of 1.0 inches. If the insulator has been removed, adjustment may be required. Loosen the 1/4-20 jam nut at the spark gap bracket and rotate the adjusting screw for the indicated spacing between the crown nut and the coupler case wall. Retorque the jam nut.

5.2.7 High Voltage Output Capacitor Selector Switch:

Location of channel 1 with respect to the switch common. Face the switch wafer from the RF output end of the coupler. Channel 1 is located adjacent to the switch common terminal in a counter-clockwise direction. Switch rotation is also counter-clockwise, therefore channel 2 is two terminals CCW from common, etc.

5.3 RF Network Adjustments:

The initial tuning of the antenna coupler is described in Section 3 OPERATION. Refer to the data given in that section for retuning to a new frequency.

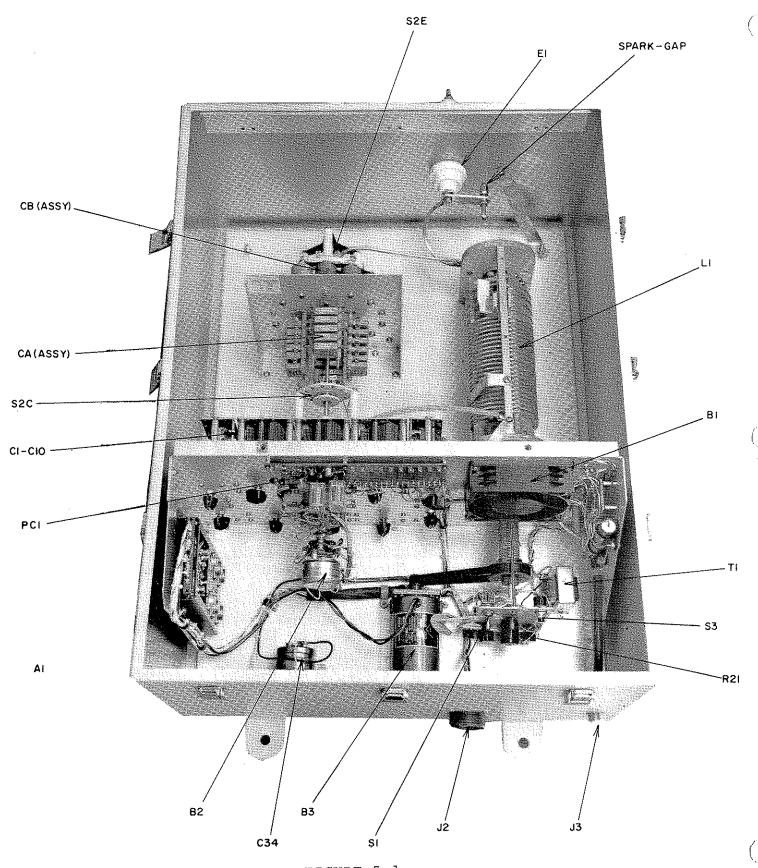
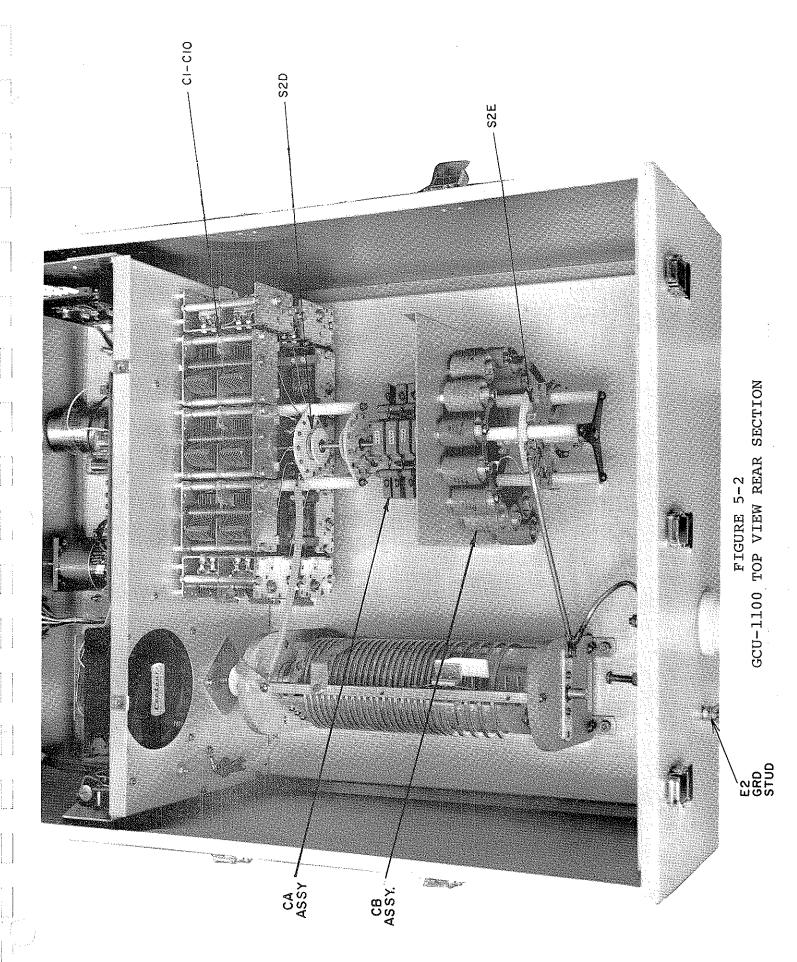
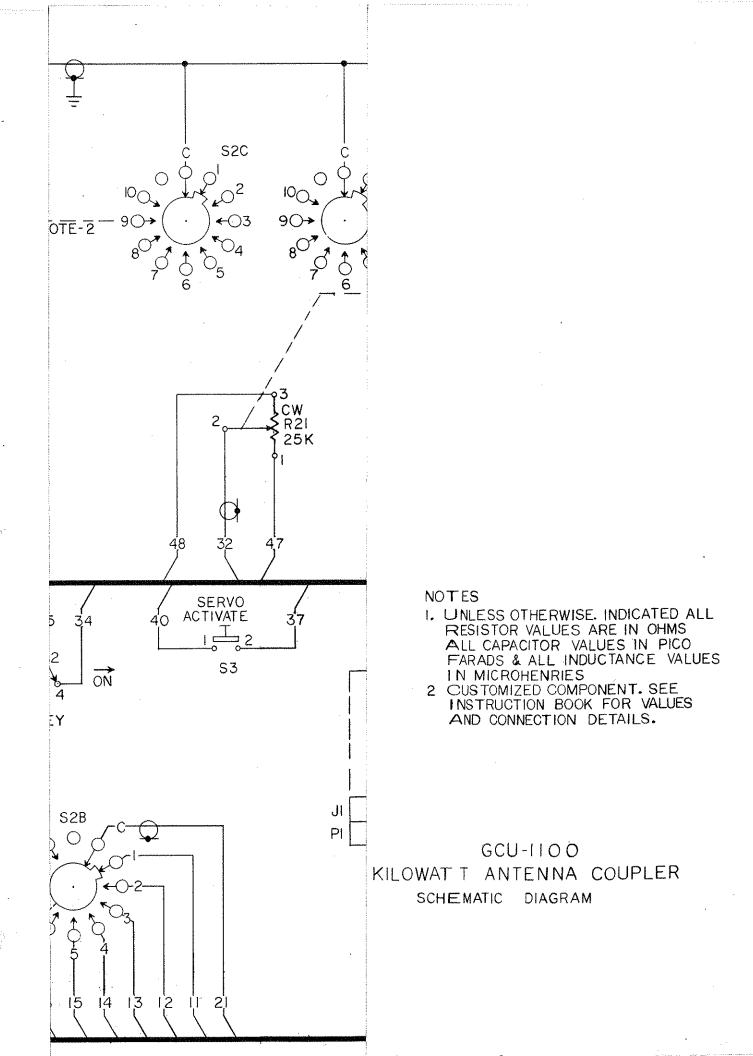


FIGURE 5-1 GCU-1100 TOP VIEW



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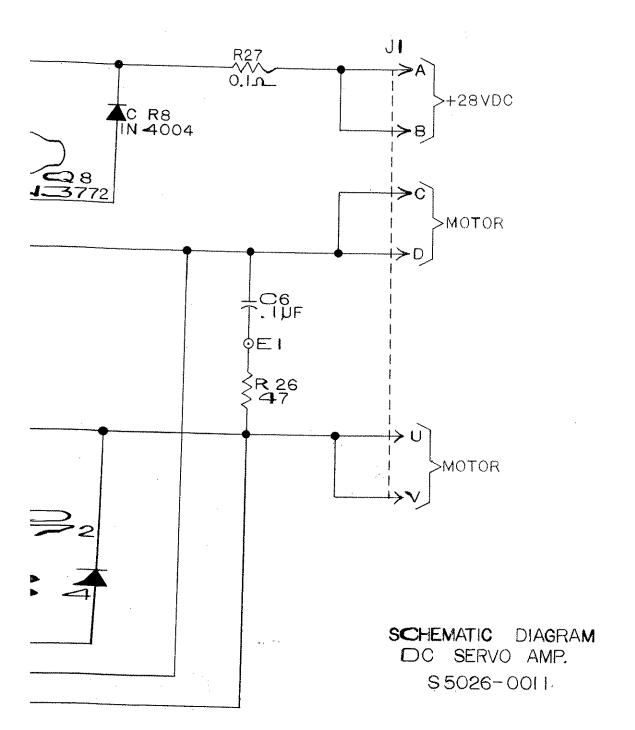


TABLE 5-L

WIRE LIST

WIRE NO.	FROM	ТО	LEBUCETH	SIZE & COLOR	DESC
l	J 2-F	P1-P		20 WHT	Grd
2	Ј2-G	XF1-1		16 Yel	115
3	Ј2-В	T1-2		16 Orange	115
4	л2-н	S2A-A		20 Brown	
5	т2-л	S2A-B		20 Red	cha
6	J2-A	S2A-C		20 Orange	Con
7	J 2-M	S2A-D		20 Yel	
8	Т2-Т	S2A~E		20 Green	
9	T2-E	XF2-1		16 Bl/Wh	+28V
10	J2-D	XF2-1		16 Red	11
11_	TB1-1	S2B-1		24 Brn	
12	TB1-2	S2B-2		24 Red	<u> </u>
13	TB1-3	S2B=3		24 Orange	<u> </u>
1/4	7°B1-4	S2B-4		24 Yel	Pot
15	TB1-5	S2B-5		24 Green	Chá Se
16	TB1-6	S2B-6		24 Blue	Cor
17	TB1-7	S2B-7		24 Violet	
18	TB1-8	S2B-8		24 Grey	<u> </u>
19	TR1-9	S2B-9		24 White	<u> </u>
20	TB1-10	S2B-10		24 Black	
27	Pl-I	S2B-Com		Shielded 20 Audio Type	Co Po
22	XF2-2	P1-A		18 Brn/Wh	+2
23	B2-1	TB1-21		20 Brn/B1/Wh	
24	TB1-20	WR2 (Anode)		20 Red/Wh	-1
25	P1-S	TB1-14		20 Green	Se
26	Pl-F	TR1-15		20 Vio/Wh	Eo
27	Pl-M	VR2-(Anode)		20 Red/Wh	-1
28	Pl-W	Motor		1.6 Red	Mo
the second of the second				······································	

TABLE 5-1 Con't
WIRE LIST

	то	LENGTH	SIZE & COLOR	DESCRIPTION
·····	Motor		16 B1k	
	VR1-(Cath)		20 Ye1/Wh	+24V Reg
<u>d</u>			Shielded	T-11 D-6
	R21-2		20 Audio	Follow Pot Wiper
****	C34 (-)		20 Ye1	
	S1-4		20 Blue	Key In
-	<u>\$1-2</u>		20 Gray/Wh	
**********************	TB1-17		20 Violet	Key Out
	S1-3		20 Green/Wh	
	VR3 (Cath)		20 B1/Wh	
	VR3/VR1	<u>'</u>	20 Black	
	P1-F		20 Drg/B1/Wh	Enable
	C34 (+)		18 Yel/Wh	+28V Unreg
				
	R22		16 Org	+28V Unreg
	C35/R2		18 Red/Wh	ři II
	VR4 (Anode)		20 Brn/Wh	-33v
	VR4 (Cath)		20 Blue/Wh	+33V
	VR4 (Cath)		20 Shld Blk	11
	VR4 (Anode)		20 Pair Wh	-33v
	,			
		·		

SECTION 6 PARTS LIST

		PARTS	LISI		
CKT. SYM.	PART NO.	DESCRIPTION	CKT. SYM.	PART NO.	DESCRIPTION
7) 1	71504	Fan, 115 VAC, 50/60 Hz			400/ 4 / 0347
B1	71594 34271	Solenoid, Rotary, 28V	R1	18538	Resistor, 10 ohm, 10% 1/2W
B2	5026-	Motor, D.C. Servo 24V	R2	19477	Resistor, 1.0 ohm, 10% 1/2W
B3	0123	Motor, D.C. Serve Dav	R3	16607	Resistor, 15K 10% 1/2W
q	0123		R4	31841	Potentiometer, 50K, 10 Turn
C1-			R5	16671	Resistor, 100K ohm 10% 1/2W
C10	27551	Capacitor, Air Var, 760PF	R6	17390	Resistor, 470 ohm 10% 1/2W
C11-	2/331	Capacitor, Ist visit is	R7	16607	Resistor, 15K ohm 10% 1/2W Potentiometer, 1 Meg 10 Turn
C29		Not Used	R8	31853	Resistor, 100K ohm 10% 1/2W
C30	27400	Capacitor, 15UF, 35V	R9	16671	Resistor, 470 ohm 10% 1/2W
C31	27544	Capacitor, 10UF, 50V	R10	17390	Resistor, 470 onin 10% 1750
C32	27400	Capacitor, 15UF, 35V	R11-	24020	Potentiometer, 25K 10 Turn
C33	28923	Capacitor, 500UF, 50V	R20	31839	Potentiometer, 25K 10 Turn
C34	28147	Capacitor, 9,500UF, 50V	R21	31865 16190	Resistor, 100 ohm 12W
C35	27230	Capacitor, 1UF, 100V	R22	16114	Resistor, 300 ohm 5W
C36	28923	Capacitor, 500UF, 50V	R23	2	Resistor, 330 ohm 10% 1W
C37	24355	Capacitor, .01UF	R24	16530 18538	Resistor, 10 ohm 10% 1/2W
		•	R25	16499	Resistor, 47 ohm 10% 1W
CA		(Quantity as Required by	R26	10499	Treatacora at outsite and and
8		Ant Type & Freq)		34626	Switch, DPDT
СВ			S1	5026-	244 Trents my p. 1
			S2A	0302	Switch, Wafer, Special
	27545	Capacitor, Ceramic, 25PF 15KV	S2B	5026-	OTTIONS TOWNS OF STREET
	27546	Capacitor, Ceramic, 50PF, 15KV	32D	0314	Switch, Wafer, Special
	29032	Capacitor, Ceramic, 25PF, 5KV	S2C	34569	
	29020	Capacitor, Ceramic, 50PF 5KV	S2D	34569	
	27550	Capacitor, Mica 220PF 2.5KV	S2E	34634	
	28204	Capacitor, Mica 470PF 2.5KV	S3	34622	
	27548	Capacitor, Mica 1000PF 2.5KV	30	3.000	***************************************
		m . A MINITO O A	T1	49162	Xfmr 115/230V
CR1	40542	Rect. Assy FWB, 2 Amps			
CR2	40541	Diode, 1N645	VR1	40189	Diode Zener 1N2986B
CR3	40541	Diode, 1N645	VR2	40538	Diode Zener 1N5349A
CR4	40541	Diode, 1N645	VR3	40538	Diode Zener 1N5349A
CR5	40165	Diode, 1N2071 Rect. Assy FWB, 2 Amps	VR4	40523	Diode Zener 1N5364B
CR6	40542	Rect. Assy r wb, 2 Amps			
F1	84110	Fuse, MDL-1	TB1		(P/O P.C. Board)
F2	89666	Fuse, MDL-3			
r2	0,5000	ruse, Mistro			
J1	1	P/O A1 (P.C. Board)			
J2	75403	Conn. MS-3102A-28-9P			
J 3A	75336				
J3B	75406				
J~D	1			İ	
K1	66743	Relay DPDT, 24VDC		ļ	
K2	66755				
					**
L1	55926	Inductor, Var. 22.5UH			EE 400
P1	75361	P/O A1 (P.C. Board)			
P2	75402			.	
P3	74219	Conn. PL-259	1 1	ł	
1.					
Q1 Q2	44833			1	1
Q2	44833				
Q3	44834			1	
Q4	44834	UJT 2N2646			
				1	1
		1			
				1	
		*		1	
6			93 E	B	

CKT. SYM		DESCRIPTION	CKT. SYM.	PART NO.	DESCRIPTION
		D.C. SERVO AMPUFIER			
<u>A1</u>		ASSEMBLY A1			·
C1 C2 C3 C4 C5 C6	28272 28715 29707 27187 27187 24408	Capacitor, 5600PF, 5% Capacitor, 200PF, 5% Capacitor, 1.022UF Capacitor, .01UF Capacitor, .01UF Capacitor, .1UF, 75V			
CR1 CR2 CR3 CR4 CR5 CR6 CR7 CR8 CR9	44290 44290 44290 44290 44290 40518 40518 40518	Diode, 1N914 Diode, 1N914 Diode, 1N914 Diode, 1N914 Diode, 1N914 Diode, 1N4004 Diode, 1N4004 Diode, 1N4004 Diode, 1N4004 Diode, 1N4004			
P1	74972	Connector, P.C.			,
Q1 Q2 Q3 Q4 Q5 Q6 Q7 Q8 Q9 Q10	44838 44838 44839 44835 44836 44836 44837 44837 44837	Transistor, 2N1711 Transistor, 2N1711 Transistor, 2N2907A Transistor, 2N1893 Transistor, 2N3741 Transistor, 2N3741 Transistor, 2N3772 Transistor, 2N3772 Transistor, 2N3772 Transistor, 2N3772 Transistor, 2N3772 Transistor, 2N3772	A NATIONAL PROPERTY OF THE PRO		
R1 R2 R3 R4 R5 R6 R7 R8 R9 R10 R11 R12 R13 R14 R15 R16 R17 R18 R20 R21 R22 R23 R24 R25 R26 R27	19348 19348 18306 17247 17481 18057 18057 17807 17352 17807 17522 17677 18186 17156 18667 17091 17091 17091 16554	Resistor, 2150 ohms 1% Resistor, 2150 ohms 1% Resistor, 5.6K, 10% 1/4W Resistor, 1.5K 10% 1/4W Resistor, 4.6.8K 10% 1/4W Resistor, 470K 10% 1/4W Resistor, 470K 10% 1/4W Resistor, 470K 10% 1/4W Resistor, 2.2K 10% 1/4W Resistor, 2.2K 10% 1/4W Resistor, 180 10% 1/4W Resistor, 180 10% 1/4W Resistor, 180 10% 1/4W Resistor, 1.2K 10% 1/4W Resistor, 1.2K 10% 1/4W Resistor, 1.2K 10% 1/4W Resistor, 1.2K 10% 1/4W Resistor, 1.0K 10% 1/4W Resistor, 1.0K 10% 1/4W Resistor, 1.0K 10% 1/4W Resistor, 330 10% 1/2W Resistor, 330 10% 1/2W Resistor, 100 10% 1W Resistor, 100 10% 1W Resistor, 100 10% 1W Resistor, 100 10% 1W Resistor, 47 10% 1W Resistor, 47 10% 1W Resistor, 0.1 10% 15W			
AR1	44733	Int. Ckt UA709			
VR1	40232	Diode, Zener 1N746			

SUNDIF

		noport			_	
3 to 5 Units For	2 TC	4 Years	MODEL GCU-1100	.00		
			SunAir P/N	Description	Unit Price	Total Price
		20	84110	Fuse l amp Slo-Blo		
		20	89666	Fuse 3 amp Slo-Blo		
		L	71594	Fan, 115 VAC 50/60 Hz 115CFM		
	2386 2480 2480		34271	Solenoid, Rotary, 28VDC		
		Т	5026-0123	Motor, D.C. Servo 24V		
		2	27551	Capacitor, Air Var 2x380pf		,
		2	28923	Capacitor, Elect 5000F		
		,1	28147	Capacitor, Elect 85°C, 9500UF		
			40542	Rect Assy, FWB 2 amp		
		Н	40518			
		-	66743	Relay DPDT 24 VDC		
		 1	66755	Relay 4 PDT "		
			55926	Inductor Var. 22.5UH		
•		,	44833	Transistor 2N697		
			44834	UJT 2N2646		
		1	31865	Potentiometer, Prec. 25K Turn		
			5026-0302	Switch, Wafer 30° Slave		
			5026-0314	Switch, Wafer 1 Pole 10 Pos		
		g	34569	Switch, Wafer, 1 Pole 12 Pos		
			34634	\sim		
			49162	Xfmr, PR1 115/2300 e44 e4A		
		,1	40189	Diode, Zener, 24V 5% 10W		
			40538	Diode, Zener, 12V 10% 5W		
		-	40523	Diode, Zener 33V 5%		

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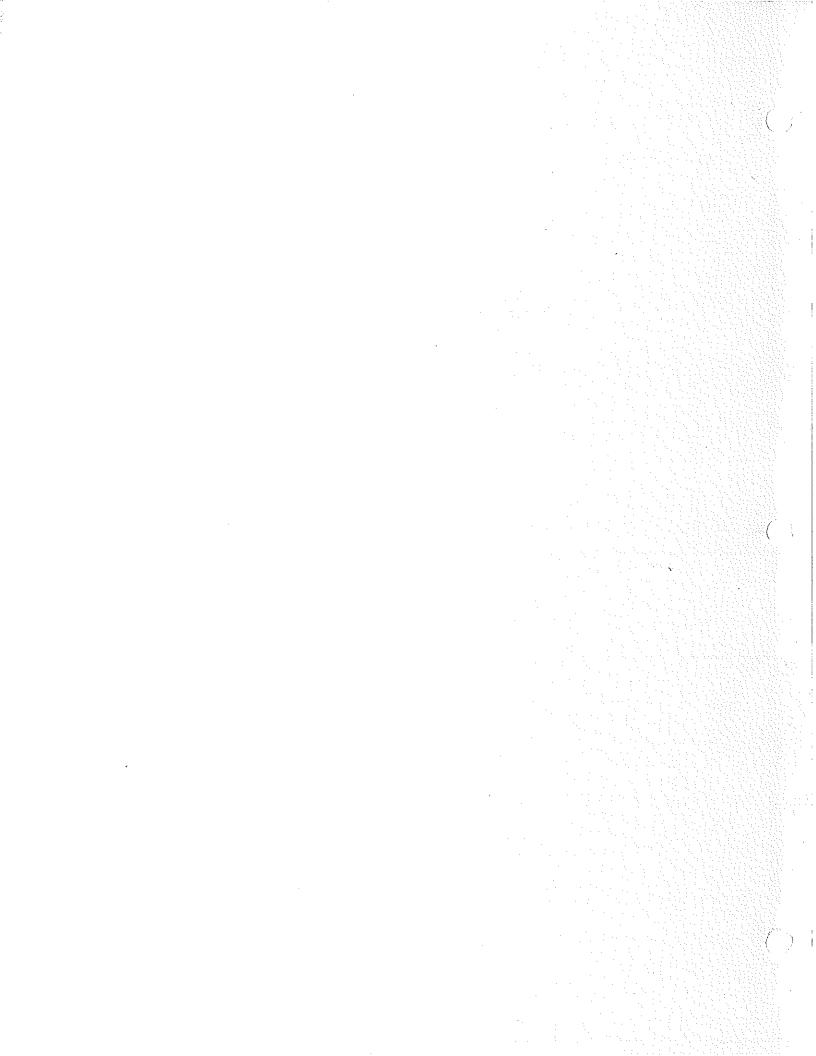


Cushi-te Dominary	J.	Silvanort				
3 to 5 Units For	2 10	Years	MUDEL GCU-1100	Voltage		
				Description	Unit Price	Total Price
		·	00-01	D.C. Servo Amp Assy		
						A STATE OF THE PARTY OF THE PAR
			CONT.			
		1	The state of the s			
		1				

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ADDENDUMS

Information contained in this section supplements the information contained in the manual. References to this section may be indicated where necessary in the manual.



SUNAIR ELECTRONICS, INC.

Manual: GCU-1100

ADDENDUM 01 **DATE:** 2-19-75

REFERENCE: GCU-1100 Kilowatt Antenna Coupler

ECN:

5026-008

EFFECTIVITY: Serial Number 174

PURPOSE:

Correct wiring error

MANUAL REFERENCE: Schematic Diagram, GCU-1100

TEXT: The arc suppressor circuit across solenoid stepping motor, B2, is incorrectly shown. The correct connections are shown below.

